## MATHEMATISCHES FORSCHUNGSINSTITUT OBERWOLFACH

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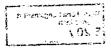
## FLÄCHEN IN DER GEOMETRISCHEN DATENVERARBEITUNG

16.04. bis 22.04.1989

Die Tagung fand unter der Leitung von R.E. Barnhill (Arizona State University, Tempe), W. Böhm (TU Braunschweig) und J. Hoschek (TH Darmstadt) statt.

Im Mittelpunkt des Interesses stand die Entwicklung neuer mathematischer Methoden und effizienter Algorithmen zur Darstellung von Kurven und Flächen des CAD. Aus der Vielfalt der vorgestellten Forschungsergebnisse seien folgende Schwerpunkte herausgegriffen: Qualitätsanalyse, Glättungsalgorithmen, Scattered Data-Interpolation über ebenen und gekrümmten Bereichen, multivariate Splines, Einsatz von Methoden der algebraischen Geometrie, Repräsentation spezieller Flächen, sphärische Splines zum Design zwangläufiger Bewegungen, geometrisch stetige Übergänge, rationale Splines, Interpolation mit Berücksichtigung geometrischer Nebenbedingungen, Polarformen zum Studium polynomieller Kurven und Flächen, Algorithmen zur graphischen Darstellung. Vorträge von Anwendern, in denen auch auf offene Fragen und Probleme der Praxis hingewiesen wurde, stellten eine wichtige Ergänzung dar.

Die regen Diskussionen im Anschluß an die Vorträge sowie die zahlreichen Gespräche im Verlauf der Tagung lieferten eine Fülle interessanter Anregungen. Als besonders wertvoll für die Befruchtung der aktuellen Forschung erwies sich der Kontakt zwischen den an Universitäten lehrenden Wissenschaftlern und den in der Industrie tätigen Mathematikern.



## Vortragsauszüge

### R. E. BARNHILL

## Geometry Processing and Surfaces on Surfaces

Geometry processing is the calculation of geometric properties of already constructed curves and surfaces. We present two geometry processing topics: Surface-surface intersections and curvature analysis. We compare our marching algorithm for surface -surface intersection with a divide and conquer algorithm. Our curvature analysis concludes that three surface curvatures, Gaussian curvature, mean curvature and absolute curvature, are useful for surface interrogation. Our surfaces defined on surfaces presentation includes a comparison of the distant-weighted method of Bruce Piper with the curved triangular interpolant of Henry Ou. Each of the above topics is illustrated by color computer graphics.

## C. M. HOFFMANN

## Surface Operations in Higher Dimensions

Operations such as offsets, Voronoi surfaces, and variable radius blending surfaces seem to require approximation or expensive symbolic computation. We propose to avoid both by using a higher dimensional formulation that considerably simplifies the numerical difficulties.

### H. POTTMANN

# Scattered Data Interpolation Based upon Generalized Minimum Norm Networks

A generalization of G.M. Nielson's method for bivariate scattered data interpolation based upon a minimum norm network is presented. The essential part of the new technique is the use of a variational principle for determination of function values as well as cross boundary derivatives over the edges of a triangulation of the data. We mainly discuss the case of C<sup>2</sup> interpolants and present some examples including quality control with systems of isophotes. Finally, extensions to spherical scattered data methods are addressed.

## T. FOLEY, R. FRANKE, D. LANE, G. NIELSON, H. HAGEN

## Interpolation of Scattered Data over Closed Surfaces

Given N arbitrary points  $p_i$  on a closed surface D and associated real values  $F_i$ , we address the problem of constructing a smooth function F(p) defined for all  $p \in D$  which satisfies  $F(p_i) = F_i$ , for i = 1,...,N. We assume that D has genus zero, that is, topologically equivalent to a sphere. The basic approach involves mapping D to a sphere, solving a corresponding scattered data interpolation problem on a sphere, and then mapping back to the domain surface D.



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## M. J. PRATT

## Smooth Blending of Circular-section Ducts using Piecewise Cyclides

The talk provides a review of recent work by the author and others in the use of cyclide surfaces for the creation of GC¹ blends between natural quadrics, toruses or other cyclides in general. The concept of the double-cyclide blend is then introduced, and detailes are given of the construction of a smooth blend between two cylindrical ducts of different diameters, at arbitrary relative positions and orientations in three dimensions. An extension to the blending of conical or more general cyclidal ducts is indicated.

## W. BOEHM

## On Cyclides in Geometric Modeling

Just 125 years ago J. Clerck Maxwell gave a nice construction of Dupin's cyclides by the use of a string. Most of their properties can be derived from this construction. Although they have a very simple Bézier representation cyclides are more suitable for solid blending than for patchwork. Some examples are given: the double-cyclide blend of two cones, a solution of the so-called Cranfield-problem, and the blend of a tripod.

#### I. HOSCHEK

## GC<sup>n-1</sup>-Functional Splines for Interpolation and Approximation of Curves. Surfaces and Solids

Implicit curves and surfaces are used for interpolation, approximation, blending of curves and surfaces and for filling holes. The method is an extension of Liming's conic section splines by introducing a power  $n \ge 2$  for the transversal curve. The constructed curves and surfaces can be used for functional splines which fulfill geometric continuity conditions.

### H. MCLAUGHLIN, B. PIPER

## Spiralarcs: An Interpolation Problem

Spiralarcs are planar curves with monotone curvature. Does there exist a spiral arc which interpolates two points with specified tangent lines and specified centers of curvature at the points? The answer is negative. Does there exist an arc with not more than one vertex which satisfies the above interpolation problem? The answer is also negative. It is conjectured that the interpolation problem can be solved with an arc of not more than two vertices.



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### M.BERCOVIER

## Related Topics in CAD and FEM: Isochoric Deformations

Using the theoretical mechanics approach the notions of deformation of a body, deformation gradient and Green Lagrange strain tensor E are introduced. Let A be the (matrix) deformation gradient, an isochoric deformation is defined by det A = 1. Isochoric deformations happen for so-called incompressible materials. The definition implies elementary volume preserving. However, isochoric deformations cannot be built using polynomial or rational deformation functions. Next one can relax the isochoric condition. It would be good enough to control the volume of a patch for instance, without controlling infinitesimal changes. This leads to so-called "mixed" type finite element approximation, with a Lagrange multiplier dual to the patch global volume constraint. A simple triquadratic case is used to illustrate this approach. As a conclusion it is shown that some nonclassical thoughts taken from the necessity of physics can help set the proper background and thus obtain a solvable problem!

#### D. LIU

## GC1 Conditions between Two Rational Bézier Patches

The GC<sup>1</sup> necessary and sufficient conditions between two adjacent rectangular or two triangular rational Bézier surface patches are presented. Further some practical and simple sufficient conditions are developed. There are many weights in the GC<sup>1</sup> conditions which are useful to easily compose a GC<sup>1</sup> smooth surface.

## T. D. DEROSE

# Necessary and Sufficient Conditions for Tangent Plane Continuity of Bézier Surfaces

Sets of conditions are derived that are necessary and sufficient for tangent plane continuity between two integral or rational Bézier surfaces. The patches may be given in either triangular or rectangular form, and no assumptions are made concerning the relative degrees of the patches; the only assumption is that the patches share common boundary control points (and weights in the case of rational surfaces). The conditions are shown to be minimal in the sense that they are, in general, independent.

## W. DEGEN

## Supplements to the Theory of Gk Continuity of Surface Patches

In a first part, reviewing the theoretical foundations, the definition of G<sup>k</sup> continuity along a common boundary curve, as recently given by J. Hahn,



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CAGD 6(1989), is compared with the notion of "contact of order k" used in differential geometry. Especially for  $G^2$ , it will be shown that the existence of a family of curves, crossing the boundary transversally with  $G^2$  continuity, is equivalent to both.

In a second part, the theory is applied to two adjacent rectangular Bezier surface patches. Recently, G. Farin's  $G^1$  construction (CGIP 20(182)), was improved by D. Liu and J. Hoschek (1989, to appear). But their solution is implicit. Using algebraic methods and the prime factorization of polynomials, an explicit solution will be obtained. By similar arguments, the analogous solution for the  $G^2$  case is derived under an additional regularity assumption.

## N. LUSCHER

## Calculation of Curvature Continuous Cubic Splines

The connection between the recursion formula for B-splines and the de Boor algorithm is well known. Using results of Goodman/Unsworth and Boehm the analogous connections for curvature continuous cubic splines are presented and special properties are discussed.

#### T.N.T. GOODMAN

## Constructing Piecewise Rational Curves with Frenet Frame Continuity

A simple geometric construction is given for the Bézier points of two rational curves which join with appropriate Frenet frame continuity. This is then used to give a geometric construction, from an arbitrary sequence of control points, for the Bézier points of a sequence of rational curves of degree n which join with Frenet frame continuity of order at most n-1.

### P. BRUNET

## Increasing the Flexibility of VC1 Connections of Bézier Patches

The problem of connecting a given patch to a neighbour (to be defined) in a VC¹ way is studied. In practical applications we would expect some data on the neighbour to be fixed (for example, boundaries). From a counting of degrees of freedom, it can be found that this is not possible. In this sense, the algorithm of Farin' 82 gives the most general solution inspite of the assumption of linearity on the coefficients of the linear and rectangular unions, and in polynomial or rational patches. After that, a method is proposed that relaxes the one-sidedness of sequential patching by modifying one control point in the data patch. The consequence is that a VC¹ connection with a neighbour with both endpoints completely uncoupled is always possible. Also, the modification of the data patch can be minimized.



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## H. NOWACKI, D. LIU, X. LÜ

## Fairing Bézier Curves with Some Constraints

A planar parametric Bézier curve is constructed from a combination of interpolation conditions, end conditions, and integral constraints such as area under the curve. A variational formulation of the problem based on a second (or higher) derivative fairness criterion is presented. It leads to a nonlinear system of equations for the free set of Bézier points, resulting from a sufficiently high degree of the Bézier curve, and for the Lagrange multiplier. The resulting curve meets all constraints and minimizes the fairness criterion. The computational effort is fairly high what suggests possible improvements by relaxing some constraints into inequalities.

#### H. PRAUTZSCH

## A Fast Algorithm to Raise the Degree of B-Spline Curves

The number of operations existing algorithms need to raise the degree of a B-spline curve  $s(x) = \sum\limits_{i=1}^{m-n} c_i \, N_i^n(x)$  by one is of order  $O(n^2m)$  where m denotes the number of knots the spline s(x) depends on and n the degree of the spline. A new algorithm is presented which is faster than the known algorithms for any degree and where the nubmer of operations needed is of order O(nm).

#### J. A. GREGORY, M. SARFAZ

#### A Rational Cubic Spline with Tension

A rational cubic spline curve is described which has tension control parameters for manipulating the shape of the curve. The spline is presented in both interpolatory and rational B-spline forms, and the behaviour of the resulting representations is analysed with respect to variation of the control parameters.

#### G. FARIN

#### Surfaces over Dirichlet Tessellations

We develop a class of surfaces that are based on the concept of Sibson's interpolant. This is a generalization of one-dimensional piecewise linear interpolation to the case of two or more variables. The interpolant is obtained as the ratio of certain areas arising in the recursive generation of Dirichlet tesselations. We reinterpret Sibson's interpolant as the projection of higher dimensional Bézier simplices and generalize to arbitrary degrees of those simplices. An application is a C<sup>1</sup> scattered data interpolant with local control and quadratic precision.



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#### G. GEISE, U. LANGBECKER

## Finite Ouadric Segments with Four Conic Boundary Segments

For suitable segments the problem is solved how to get a representation as rational TP Bézier surface which is smooth in the sense of differential geometry and which has the boundary curves as u and v lines. The intuitive idea of sweeping out the surface by one conic may be realized by application of known facts concerning rational Bézier representation of conics in the view of stereographic projection. The resulting representation x(u,v) is of degree  $m \le 6$  in u and of degree  $n \le 2$  in v. Some special problems are considered too.

### A.WORSEY

## Contouring Quadratics for Surface Analysis

We consider the problem of robustly contouring a trivariate quadratic polynomial defined over a tetrahedron. We show how the contour can always be described by a collection of rational quadratic patches. These patches are easily parametrized after considering the contouring problem on faces of the tetrahedorn. A <u>completely</u> robust method for solving this problem is also developed which, to within machine accuracy, describes these contour curves as rational quadratics with non-negative weights.

#### M. LUCIAN

# Convexity Preserving and Curvature Continuous Interpolating Ouadratic Rational B-Spline

An algorithm, symmetric in the input, is provided which interpolates a planar set of data without introducing inflections extraneous to the data. The two main features of the output (convexity and curvature continuity) are independent. A simple extension allows for interpolating data with associated curvatures.

#### R. KLASS

## Solved and Unsolved Surface Problems in Car Body Design

- 0 Intersection problems and solutions
- Offset surfaces and singular points
- Collisions problems between algebraic and parametric surfaces
- O Approximation with boundary conditions
- 0 Controlling surface shape
- o Design and milling problems with "Multisurfaces"



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#### N. PFEIFF

## Using CAGD Methods in the System CASS for Styling Applications

#### C. de BOOR

## Multivariate Polynomial Interpolation

With M a subset of d-space and Q a polynomial space, call the pair (M,Q) correct in case interpolation from Q at M is possible and uniquely so, i.e. in case the map on Q which carries the funcion f to its restriction to M is 1-1 and onto.

The joint work with Amos Ron reported on provides a map which associates with each finite subset M of d-space a polynomial space P(M) so that (M,P(M)) is correct. The map has the following properties: (i) P(M) is defined for every finite M. (ii) P(M) depends continuously on M (to the extent possible). (iii) (acceptable) coalescence leads to osculation. (iv) P(M) is translation-invariant, hence D(ifferentiation)-invariant. (v) P(M) is scale-invariant, hence spanned by homogeneous polynomial. (vi) For any invertible matrix A,  $P(AM) = P(M)A^T$ . (vii) P(M) is of minimal degree, in the sense that, for any correct (M,Q) and any j, dim  $Q_j \leq \dim P(M)_j$  (with  $Q_j$  denoting the space of all polynomials of degree  $\leq j$  in Q). (viii) The map is monotone (hence a Newton form is available for the interpolating polynomial). (ix)  $P(M \times N) = P(M) \times P(N)$  (with  $M \times N$  the cartesian product and  $P(M) \times P(N)$  the tensor product). (x) P(M) is constructible from M in finitely many arithmetic steps.

Any such map must give the standard polynomial spaces in standard situations. Further, any polynomial in P(M) must be constant in any direction perpendicular to the affine hull of M.

P(M) is constructed as the 'least' of the space  $H := \exp_M := the span of all exponentials <math>e_{m(x)} := \exp(m.x)$  with m in M. This means that P(M) is the span of all 'least's of functions in H. One finds the 'least' of a function f as the first nontrivial term  $f_k$  in the Taylor expansion  $f = f_0 + f_1 + ... + f_k + ...$  in which  $f_k$  contains all terms of (exact) degree k.

## P. ALFELD

## Multivariate Splines

Splines (i.e. smooth piecewise polynomial functions) are used universally throughout problems involving functions of one variable. It is natural to contemplate the use of similar functions in the case of several variables. However, problems that are trivial for one independent variable turn out to be extremely difficult in the case of two or more variables. In this talk, some unsolved problems concerning multivariate splines will be described and some new results will be given.



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#### L. L. Schumaker

### Data Dependent Triangulation

We consider the standard problem of fitting a surface to scattered data. Our method is based on using C<sup>1</sup> piecewise cubics on the Clough-Tocher split of a triangulation of the data. The main idea is to define a swap test for changing the triangulation based on reducing the energy of the surface. By using this swap thest, one can create data-dependent triangulations which provide surfaces with improved smoothness and better fits than those obtained using the usual Delaunay triangulation. The energy expressions are obtained in terms of the Bernstein-Bézier representation of the splines.

## R. WALTER

## Differential Geometry and Surface Rendering

We develop a method for generating and employing contours and (self)intersections of arbitrary smooth surfaces for the purpose of visibility clarifying. The result relies on differential geometric integer invariants, called sight indices which describe the change of visibility. These are the means to render distinguished curves like contours, (self)intersections, and boundaries, including visibility. In the same manner, but with different types of index formulas, arbitrary curves can be rendered. Also, more than one surface is allowed. One advantage is that the (visible parts of) curves are drawn in one stroke. Thus the method is especially suitable for gnerating high quality plots on plotters.

## W. DAHMEN

## Some Remarks on Convexity Preserving Interpolation

Given any finite set of points in  $\mathbb{R}^3$  a method for constructing a tangent plane continuous piecewise quadratic surface with prescribed topology is described. This method interpolates the given data with prescribed normal directions. In particular when the data come from a convex surface, i.e. when a convex piecewise triangular interpolant exists, conditions are discussed that ensure the piecewise quadratic interpolant to be convex as well. Specifically, the role of a certain free shape parameter in this context is illustrated by some graphical examples. Efficient ways of rendering the quadrics are indicated.

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#### N. DYN

## Recursive Subdivision Curves and Surfaces

A family of interpolatory subdivision schemes with tension control for the design of curves and surfaces is reviewed. Smoothness properties of the limit curves/surfaces are discussed and the performance of the schemes is demonstrated by several pictures. In particular, the effect of the tension parameters is tested. All the schemes above are shown to be perturbations of known schemes, with the tension parameter controlling the size of the perturbation. Small positive values of the tension parameter yield a scheme which produces a limit curve/surface with one more degree of smoothness.

#### R. N. GOLDMAN

## Algorithms in the Style of Boehm and Sablonniere

The de Boor algorithm can be extended to curves which are not strictly B-splines by allowing either infinite or decreasing knots. Blossoming can then be applied recursively to these curves to compute the dual functionals of the corresponding polynomial bases. This observation leads to change of basis formulas which are the analogues of knot insertion techniques for B-splines. These methods are applied to generate transformations between the B-spline, Bézier, monomial, and power forms of a curve which are the direct analogues of Boehm's knot insertion algorithm and Sablonniere's algorithm for converting from B-spline to Bézier form.

## H.-P. SEIDEL

## Symmetric Recursive Algorithms for Curves and Surfaces

We introduce the concept of a symmetric recursive algorithm and show that in the case of curves this leads to B-splines. We then apply this concept to surfaces and construct a new patch-representation for bivariate polynomials: The B-Patches share many properties with B-spline segments: Besides their control points they are influenced by a 3-parameter family of knots. If all knots coincide, we obtain the Bézier representation of a bivariate polynomial w.r.t.  $\Delta(R,S,T)$ . Therefore B-Patches are a generalization of Bézier patches. B-Patches have a de Boor like evaluation algorithm, and, as in the case of B-spline curves, the control points of a B-Patch can be computed by simply inserting a sequence of knots into the corresponding polar form. In particular this implies linear independence of the blending functions. Furthermore, B-Patches can be joined smoothly and they have an algorithm for knot insertion that is completely similar to Boehm's algorithm for curves.

After studying B-Patches we go back to curves and somewhat relax our symmetry conditions. This leads to geometric spline curves. In particular we show that  $\beta$ - and  $\gamma$ -splines have a de Casteljau type evaluation algorithm that starts with the given spline control points and computes the function value by repeated linear interpolation. This is surprising since it has been previously conjectured that no such algorithm for  $\beta$ - and  $\gamma$ -splines exists.



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### L. RAMSHAW

## The Progressive Case of the de Casteliau Algorithm for Surfaces

The de Casteljau Algorithm for curves has two variants. The <u>plain case</u> evaluates a plynomial curve segment given the coefficients of its Bernstein expansion, that is, its Bézier points. The <u>progressive case</u> evaluates a spline curve given the coefficients of its B-spline expansion. It turns out that the de Casteljau Algorithm for surfaces can also be extended from the plain case to an analogous progressive case. Unfortunately, the resulting algorithm cannot be applied in any straightforward way to evaluate --say--a box spline surface. Both polar forms and the symmetric variant of the tensor-product construction are useful in studying this situation.

### M. DÆHLEN, T. DOKKEN, T. LYCHE, K. MØRKEN

# Almost Best Approximation of Circles by Curvature-continuous Bézier Curves

We provide a surprisingly simple cubic Bézier curve which gives a 6-th order accurate approximation to a segment of a circle. Joining the Bézier segments we obtain a G<sup>2</sup>-continuous approximation to the circle. The error is approximately onetenth of what is obtained by applying the general method of de Boor, Höllig and Sabin to the case of a circle.

#### T. LYCHE

#### Exponential B-splines in Tension

Splines in tension were introduced by Schweikert in 1966 as a means of eliminating wiggles in cubic spline interpolation. We will construct a B-spline representation for tension splines allowing multiple knots and different tension parameters  $\rho_1$  and linear B-splines for large values of  $\rho_1$ . The result is a local representation for a class of functions which has the smoothness of a cubic spline and the shape of a piecewise linear approximation.

### K. HÖLLIG, H. MÖRGELE

### **G-Solines**

We introduce a new type of spline spaces for constructing  $GC^{n-1}$  surfaces for (general) networks of n-th degree Bézier patches. In particular, "G-Splines" allow to incorporate singular vertices (the number of coincident patches does not equal 4) into a tensor product network. Our approach is based on an idea of Goodman for constructing biquadratic  $GC^1$  tensor product patch networks and a special choice of the Geometric Continuity constraints.



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## I. PETERS

## On Smoothness and Compatibility

#### R. PIPER

## Fill-in Regions for Curves and Surfaces

The problem of designing surfaces by using sectional curves motivates the consideration of 'curves' and this can be 'shaped' automatically by use of fill-in regions. Results of an interpolation-like algorithm that produces 'fat' planar curves will be presented along with a preliminary algorithm to use "fat" curves in the creation of surfaces.

## R. T. FAROUKI

## Analytic, Algebraic and Topological Properties of Plane Offset Curves

Although the notion of a "parallel" curve dates back to Leibnitz, such loci merit only passing mention in contemporary differential geometry books. Recently, however, they have enjoyed a resurgence of interest motivated by their applications in areas such as N.C. machining, geometry optics, tolerance analysis, and path-planning. We examine certain fundamental properties of offset curves form an analytical, algebraical, and topological perspective. Irregular points arise on an offset whenever the generator curvature attains a certain critical value, an they may be cusps (sudden tangent inversions) or extraordinary points (tangent-continuous points of infinite curvature). Further, there exists a one-to-one correspondence between certain regular "characteristic" points (turning points, inflections, and vertices) on a given generator curve and each of its offsets.

From the algebraic perspective, we show that the "interior" and "exterior" offsets to a polynomial generator of degree n, taken together, constitute an algebraic curve of degree 4n- in general. A simple closed-form expression for the implicit equation of the offset is presented, and it is seen that the degree is reduced by 2 for each "cusp" of the generator. Algebraic methods also furnish an algorithmic basis for identifying all self-intersections of the offset which are required when "trimming" it.

#### G. M. NIELSON

## Sphere Splines with Application

Based upon control points on the surface of a sphere, we introduce a new piecewise, C<sup>2</sup>, curve which remains on the sphere. The construction of this curve is analogous to cubic B-splines where the individual cubic segments are represented as Bernstein/Bézier curves. The spherical analogs of the Bernstein/Bézier curves are defined by means of a spherical version of the



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de Casteljau algorithm based upon geodesic interpolation on the sphere rather than linear interpolation. Several of the basic properties of these new curves are established and some examples are given. Using quarternions and a 4D extension of our spherical curve we show how to animate rotations.

## R. K.E. ANDERSSON

## Curves as Boundaries of Surfaces with Prescribed Shape

We will discuss the problem to generate parametric polynomial space curves, close to a set of fitting points and satisfying constraints. The constraints are derived from desired properties of the surfaces, to be bounded by a network of these curves. The need to satisfy the conditions while keeping the curve close to the fitting points gives rise to quadric minimization problems with nonlinear constraints. The solution process for these problems, however, is facilitated by benefitting from their separable character.

#### D. FERGUSON

## Directions in Curve and Surface Design

Curves and surfaces which are appropriate for manufacturing are difficult to define. In this talk a brief review of the problems will be given. Then, two approaches will be described. The first approach is constrained fitting of data and can be described as a success. The second is a variant of the TFI method of curve blending and represents work in progress.

Berichterstatter: H. Pottmann



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## Tagungsteilnehmer

Prof. Dr. P. Alfeld Dept. of Mathematics University of Utah

Salt Lake City , UT 84112 USA

Prof. Dr. R. Anderson Volvo Data AB

S-40508 Goeteborg

Prof. Dr. R. E. Barnhill Computer Science Department Arizona State University

Tempe , AZ 85287 USA

Prof. Dr. M. Bercovier Institute of Mathematics The Hebrew University Givat-Ram

91904 Jerusalem ISRAEL

Prof.Dr.-Ing. W. Boehm Angewandte Geometrie und Computergraphik TU Braunschweig Pockelsstr. 14

3300 Braunschweig

Prof. Dr. C. de Boor Center for the Mathematical Scienc. University of Wisconsin-Madison

610 Walnut Street Madison , WI 53706 USA

Prof. Dr. P. Brunet
Dept. de Metodos Informatic.
ETSEIB
UPC
Diagonal 647

E-08028 Barcelona

Dr. M. Daehlen Senter for Industriforskning Forskningsun. 1, Blindern

N-0314 Oslo 3

Prof. Dr. W. Dahmen Institut für Mathematik III der Freien Universität Berlin Arnimallee 2-6

1000 Berlin 33

Dr. W. Dankwort Abt. EK-72 BMW AG München Postfach 40 02 40

8000 München 40



Prof. Dr. W. Degen Mathematisches Institut B der Universität Stuttgart Pfaffenwaldring 57 Postfach 80 11 40

7000 Stuttgart 80

Prof. Dr. T. D. DeRose Department of Computer Science University of Washington

Seattle, WA 98195 USA

Prof. Dr. N. Dyn Dept. of Mathematics Tel Aviv University Ramat Aviv P.O. Box 39040

Tel Aviv , 69978

F. Elsässer Electronic Data Systems (Deutschland) GmbH CAD/CAM Systems Eisenstraße 56

6090 Rüsselsheim

Prof. Dr. G. Farin Computer Science Department Arizona State University

Tempe , AZ 85287 USA Dr. R. T. Farouki Sloan School of Management Massachusetts Institute of Technology 77, Massachusetts Avenue

Cambridge , MA 02139 USA

Dr. D. Ferguson Scientific Computing & Analysis Boeing Computer Services P. O. Box 24346, MS 7L-20

Seattle , WA 98124-0346 USA

Prof. Dr. T. Foley Computer Science Department Arizona State University

Tempe , AZ 85287 USA

Prof. Dr. H. Frank Fachbereich Mathematik der Universität Dortmund Postfach 50 05 00

4600 Dortmund 50

Prof. Dr. R. Franke Office of Naval Research Branch Office, London 223/231 Old Marylebone Road

GB- London NW1 5TH



Prof. Dr. G. Geise Sektion Mathematik Technische Universität Dresden Mommsenstr. 13

DDR-8027 Dresden

Prof. Dr. J. G. Hayes Division of Information Technology and Computing National Physical Laboratory

GB- Teddington, Middlesex TW11 OLW

Prof. Dr. R. N. Goldman Dept. of Computer Science University of Waterloo

Waterloo, Ontario N2L 3G1 CANADA Dr. G. Herron Computer Science Department Colorado State University

Fort Collins , CO 80523

7000 Stuttgart 80

Dr. T. N. T. Goodman Dept. of Mathematics and Computer Science University of Dundee

GB- Dundee , DD1 4HN

Prof. Dr. K. Höllig Mathematisches Institut A der Universität Stuttgart Pfaffenwaldring 57 Postfach 560

Dr. J. A. Gregory Dept. of Mathematics and Statistics Brunel University

GB- Uxbridge, Middlesex , UB8 3PH

Dr. C. M. Hoffmann Department of Computer Sciences 224, Computer Science Building Purdue University

West Lafayette , IN 47907 USA

Prof. Dr. H. Hagen Fachbereich Informatik der Universität Kaiserslautern Postfach 3049

6750 Kaiserslautern

Prof. Dr. J. Hoschek Fachbereich Mathematik der TH Darmstadt Schloßgartenstr. 7

6100 Darmstadt





Dr. R. Klass Abt. EP/ADTK Daimler-Benz AG Postfach 226

7032 Sindelfingen

Prof. Dr. T. Lyche Institute of Informatics University of Oslo P. O. Box 1080 Blindern

N-0316 Oslo 3

D. Lasser Fachbereich Mathematik der TH Darmstadt Schloßgartenstr. 7

6100 Darmstadt

Prof. Dr. H. W. McLaughlin Dept. of Mathematics Rensselaer Polytechnic Institute

Troy , NY 12180-3590 USA

Prof. Dr. Liu Dingyuan Dept. of Mathematics Fudan University

Shanghai CHINA Prof. Dr. Ch.A. Micchelli IBM Corporation Thomas J. Watson Research Center P. O. Box 218

Yorktown Heights , NY 10598 USA

Prof. Dr. M. Lucian Geometry Systems, MS 6E-27 Boeing Commercial Airplanes P. O. Box 3707

Seattle , WA 98124

Prof. Dr. G. M. Nielson Computer Science Department Arizona State University

Tempe , AZ 85287 · USA

N. Luscher Department of Mathematics Naval Postgraduate School

Monterey , CA 93943 USA Prof. Dr. H. Nowacki Institut für Schiffs- und Meerestechnik Technische Universität Berlin Salzufer 17 - 19

1000 Berlin 10

Prof. Dr. J. Peters Center for the Mathematical Scienc. University of Wisconsin-Madison 610 Walnut Street

Madison , WI 53706 USA Dr. H. Prautzsch Mathematics Dept. Rensselaer Polytechnic Institute

Troy , NY 12180 -3590 USA

N. Pfeiff Forschung und Entwicklung E/IT-KS VOLKSWAGEN AG Postfach

3180 Wolfsburg 1

Dr. L. Ramshaw Digital Equipment Corporation Systems Research Center 130 Lytton Avenue

Palo Alto , CA 94301 USA

B. Piper
Dept. of Mathematics
Rensselaer Polytechnic Institute

Troy , NY 12180-3590 USA Prof. Dr. R. F. Sarraga Computer Science Department General Motors Research Labs. 30500 Mount Road

Warren MI 48090-9055

USA

Prof. Dr. H. Pottmann Institut für Geometrie der TU Wien Wiedner Hauptstr. 8 - 10

A-1040 Wien

Prof. Dr. L. L. Schumaker Dept. of Mathematics Vanderbilt University P.O. Box 1589

Nashville , TN 37235 USA

Prof. Dr. M. J. Pratt
Dept. of Mathematics and
Applied Computing
Cranfield Institute of Technology
Cranfield

GB- Bedford , MK43 OAL

Dr. H. P. Seidel Institut für Informatik Graphisch-Interaktive Systeme Auf der Morgenstelle C 9

7400 Tübingen



Prof. Dr. W. Straßer Institut für Informatik Graphisch-Interaktive Systeme Auf der Morgenstelle C 9

7400 Tübingen

Prof. Dr. R. Walter Fachbereich Mathematik, der Universität Dortmund Postfach 50 05 00

4600 Dortmund 50

Dr. A. J. Worsey Department of Mathematical Sciences University of North Carolina at Wilmington

Wilmington , NC 28403-3297 USA







